

# TMRW1A Torque Motor

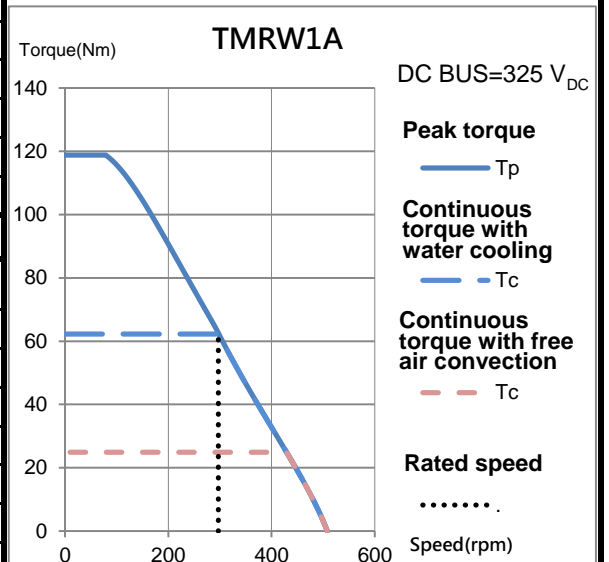
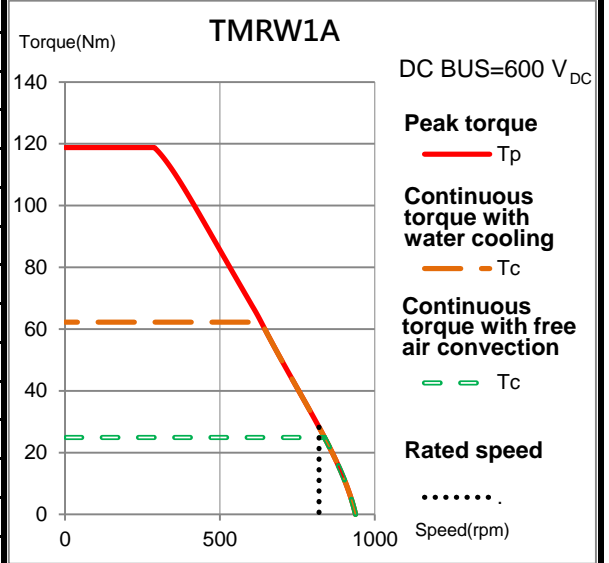
## Electrical specifications

Winding code : LA	Symbol	Unit	Free air convection	Water cooling
Continuous torque	$T_c$	Nm	24.9	62.5
Continuous current	$I_c$	$A_{rms}$	4	10
Stall torque	$T_s$	Nm	17	44
Stall current	$I_s$	$A_{rms}$	2.8	7
Peak torque(for 1sec.)	$T_p$	Nm	73	118.8
Peak current(for 1sec.)	$I_p$	$A_{rms}$	12	27
Torque constant	$K_t$	Nm/Arms	6.23	
Electrical time constant	$T_e$	ms	4	
Resistance (line to line at 25°C)	$R_{25}$	$\Omega$	7.7	
Inductance (line to line)	$L$	mH	31	
Number of poles	$2p$		22	
Back emf constant (line to line)	$K_v$	Vrms/rad/s	3.6	
Motor constant (at 25°C)	$K_m$	Nm/ $\sqrt{W}$	1.83	
Thermal resistance	$R_{th}$	K/W	0.51	0.082
Thermal sensor			PTC SNM100+SNM120+Pt1000	
Max. DC BUS		$V_{DC}$	750	
Inertia of rotor	$J$	$kgm^2$	0.0033	
Thermal time constant	$T_{th}$	s	2690	74
Max. continuous power dissipation	$P_c$	W	253	1585
Max. peak power dissipation	$P_p$	W	11558	
Rated speed(at 600VDC)		rpm	820	

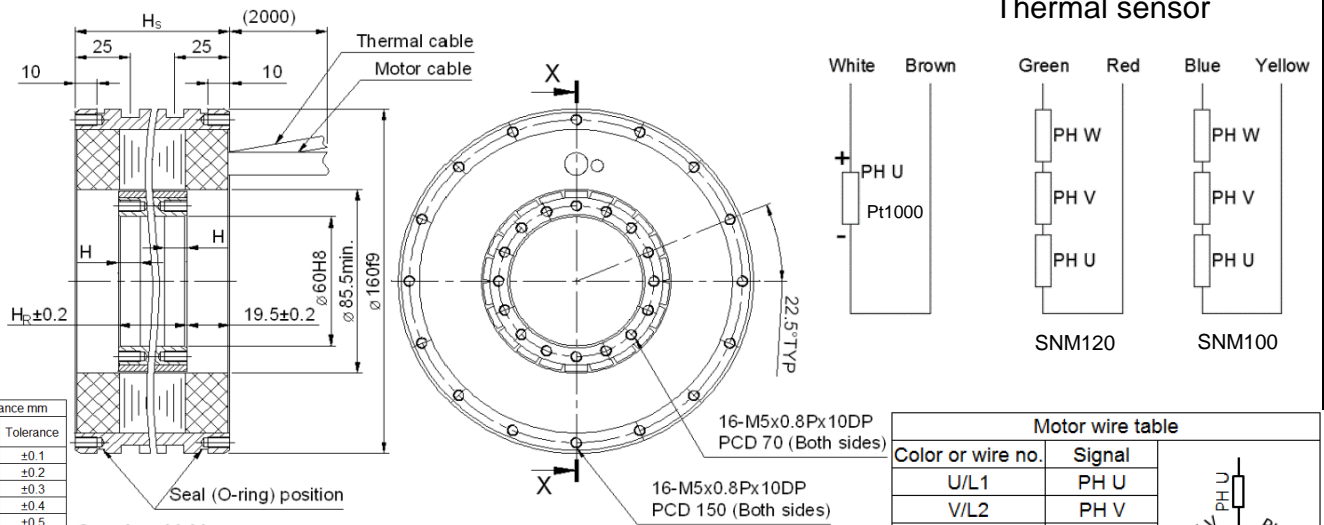
## Mechanical specifications

	Symbol	Unit	Free air convection	Water cooling
Mass of rotor	$M_r$	kg	2	
Mass of stator	$M_s$	kg	8.6	
Height of stator	$H_s$	mm	140	
Height of rotor	$H_r$	mm	101	
Length of rotor centring fit	$H$	mm	15	
Water temperature difference for $P_c$	$\Delta\theta$	K	-	5
Minimum water flow	$q$	l/min	-	4.6
Max. pressure drop	$\Delta p$	bar	-	1

## T-N curve



## Thermal sensor



General tolerance mm	
Nominal dimension	Tolerance
~ 6	±0.1
> 6 ~ 30	±0.2
> 30 ~ 120	±0.3
> 120 ~ 300	±0.4
> 300 ~ 600	±0.5
> 600 ~ 1200	±0.8
> 1200 ~ 2400	±1.0
> 2400	±1.5

Except dimensions, all the specifications in the table are in ±10% of tolerance

This drawing is only for reference, detail dimensions please refer to approval drawing.

Version: 2.00

Date: 2020/10/23